

PICTURES OF QUANTUM MECHANICS

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SCHRÖDINGER PICTURE

- BASE VECTORS OF OPERATORS ARE FIXED IN TIME (EXCEPT WHEN THE OPERATOR HAS EXPLICIT TIME DEPENDENCE)
- STATE VECTORS (DESCRIBING PHYSICAL SYSTEMS) HAVE EXPLICIT TIME DEPENDENCE \Rightarrow CHANGE IN TIME

SCHRÖDINGER EQUATION: $i\hbar \frac{d}{dt} |\Psi_S(t)\rangle = H_S(t) |\Psi_S(t)\rangle$

SOLUTION: $|\Psi_S(t)\rangle = U_S(t, t_0) |\Psi_S(t_0)\rangle$
 \downarrow
TIME EVOLUTION OPERATOR

$$U_S(t_0, t_0) = \mathbb{1}$$

$$U_S^\dagger(t, t_0) = U_S^{-1}(t, t_0) = U_S(t_0, t)$$

\uparrow
UNITARY

$$|\Psi_S(t+dt)\rangle = |\Psi_S(t)\rangle + \frac{dt}{i\hbar} H_S(t) |\Psi_S(t)\rangle$$

$$= \left(\mathbb{1} + \frac{dt}{i\hbar} H_S(t) \right) |\Psi_S(t)\rangle$$

$\underbrace{\hspace{10em}}_{U_S(t+dt, t)}$

BUT $\frac{dU_S(t, t_0)}{dt} \stackrel{dt \rightarrow 0}{=} \frac{U_S(t+dt, t_0) - U_S(t, t_0)}{dt}$

$$= \left(\frac{U_S(t+dt, t_0) U_S^{-1}(t, t_0) - \mathbb{1}}{dt} \right) U_S(t, t_0)$$
$$= \left(\frac{U_S(t+dt, t) - \mathbb{1}}{dt} \right) U_S(t, t_0)$$

$$\Rightarrow \frac{d}{dt} U_S(t, t_0) = \left(\frac{\mathbb{1} + \frac{dt}{i\hbar} H_S(t) - \mathbb{1}}{dt} \right) U_S(t, t_0)$$

$$i\hbar \frac{d}{dt} U_S(t, t_0) = H_S(t) U_S(t, t_0)$$

ALTERNATIVELY,

$$i\hbar \frac{d}{dt} (U_S |\Psi_S(t_0)\rangle) = H_S(t) U_S |\Psi_S(t_0)\rangle$$

SINCE $\frac{d}{dt} |\Psi_S(t_0)\rangle = 0$

$$\Rightarrow \left(i\hbar \frac{d}{dt} U_S = H_S U_S \right)$$

NOTICE THAT $U(t, t_0) = U(t_0 + mdt, t_0 + (m-1)dt) \dots U(t_0 + 2dt, t_0 + dt) U(t_0 + dt, t_0)$ (2)

$$= \left[1 + \frac{dt}{i\hbar} H_S(\text{at } t_0 + (m-1)dt) \right] \dots \left[1 + \frac{dt}{i\hbar} H_S(t_0) \right]$$

FOR $\frac{\partial H_S}{\partial t} = 0 \Rightarrow U(t, t_0) = \lim_{m \rightarrow \infty} \left(1 + \left(\frac{t-t_0}{i\hbar} \right) H_S \right)^m$

$$= \cancel{e^{\frac{t-t_0}{i\hbar} H_S}} = e^{-\frac{i}{\hbar} (t-t_0) H_S}$$

FOR $H_S(t_1) \neq H_S(t_2) \Rightarrow$ IN GENERAL $[H_S(t_1), H_S(t_2)] \neq 0$

$$\Rightarrow e^{\frac{dt}{i\hbar} H_S(t_1)} e^{\frac{dt}{i\hbar} H_S(t_2)} \neq e^{\frac{dt}{i\hbar} (H_S(t_1) + H_S(t_2))}$$

- AVERAGES: $\langle O_S \rangle = \langle \Psi_S(t) | O_S | \Psi_S(t) \rangle$

$$\Rightarrow i\hbar \frac{d}{dt} \langle O_S \rangle = \underbrace{\left(i\hbar \frac{\partial}{\partial t} \langle \Psi_S | \right)}_{-\langle \Psi_S | H_S} O_S | \Psi_S \rangle + \langle \Psi_S | O_S \underbrace{\left(i\hbar \frac{\partial}{\partial t} | \Psi_S \rangle \right)}_{H_S | \Psi_S} + \langle \Psi_S | i\hbar \frac{\partial O_S}{\partial t} | \Psi_S \rangle$$

$$\Rightarrow \boxed{i\hbar \frac{d}{dt} \langle O_S \rangle = \langle [O_S, H_S] \rangle + i\hbar \langle \frac{\partial O_S}{\partial t} \rangle}$$

EXERCISE: SHOW THAT THE DENSITY OPERATOR $\rho_S = |\Psi_S(t)\rangle \langle \Psi_S(t)|$ HAS, ON AVERAGE, NO EXPLICIT TIME DEPENDENCE

ANSWER: $\bullet \langle \rho_S \rangle = \langle \Psi(t) | \rho_S | \Psi(t) \rangle = 1 \Rightarrow \frac{d}{dt} \langle \rho_S \rangle = 0$

$\bullet \langle [\rho_S, H_S] \rangle = \langle \Psi_S | \Psi_S \rangle \langle \Psi_S | H_S | \Psi_S \rangle - \langle \Psi_S | H_S | \Psi_S \rangle \langle \Psi_S | \Psi_S \rangle = 0$

NOW USING THAT $i\hbar \frac{d}{dt} \langle \rho_S \rangle = \langle [\rho_S, H_S] \rangle + i\hbar \langle \frac{\partial \rho_S}{\partial t} \rangle$

$$\Rightarrow \boxed{\langle \frac{\partial \rho_S}{\partial t} \rangle = 0}$$

• HEISENBERG PICTURE

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- BASE VECTORS OF OPERATORS ARE TIME DEPENDENT
 \Rightarrow OPERATORS ARE TIME DEPENDENT

- STATE VECTORS OF PHYSICAL SYSTEMS ARE FIXED IN TIME

DICTIONARY BETWEEN THE REPRESENTATIONS

$$\begin{cases} |\Psi_S(t)\rangle = U_S(t, t_0) |\Psi_S(t_0)\rangle = U_S(t, t_0) |\Psi_H\rangle \\ \mathcal{O}_H(t) = U_S^\dagger(t, t_0) \mathcal{O}_S U_S(t, t_0) \rightarrow \text{TIME-DEPENDENT CANONICAL TRANSFORMATION} \end{cases}$$

- IMPORTANT
- (a) OPERATORS HAVE THE SAME SPECTRUM IN BOTH REPRESENTATIONS
 - (b) INNER PRODUCT BETWEEN 2 STATES ARE THE SAME
 - (c) AVERAGES OF OBSERVABLES ARE THE SAME

$$\begin{aligned} \langle \mathcal{O}_S \rangle &= \langle \Psi_S(t) | \mathcal{O}_S | \Psi_S(t) \rangle = \langle \Psi_S(t_0) | U^\dagger(t, t_0) \mathcal{O}_S U(t, t_0) | \Psi_S(t_0) \rangle \\ &= \langle \Psi_H | \mathcal{O}_H(t) | \Psi_H \rangle = \langle \mathcal{O}_H \rangle \end{aligned}$$

"EQUATION OF MOTION" FOR THE OPERATORS

$$i\hbar \frac{d}{dt} \mathcal{O}_H = \underbrace{\left(i\hbar \frac{\partial U_S^\dagger}{\partial t} \right) \mathcal{O}_S U_S}_{-U_S^\dagger H_S} + \underbrace{U_S^\dagger \mathcal{O}_S \left(i\hbar \frac{\partial U_S}{\partial t} \right)}_{H_S U_S} + \underbrace{i\hbar U^\dagger \left(\frac{\partial \mathcal{O}_S}{\partial t} \right) U}_{i\hbar \frac{\partial \mathcal{O}_H}{\partial t} \text{ (DEFINITION)}}$$

$$i\hbar \frac{d}{dt} \mathcal{O}_H = U_S^\dagger \mathcal{O}_S U_S U_S^\dagger H_S U_S - U_S^\dagger H_S U_S U_S^\dagger \mathcal{O}_S U_S + i\hbar \frac{\partial \mathcal{O}_H}{\partial t}$$

$$i\hbar \frac{d}{dt} \mathcal{O}_H = [\mathcal{O}_H, H_H] + i\hbar \frac{\partial \mathcal{O}_H}{\partial t}$$

RESEMBLES THE EQUATION FOR $\langle \mathcal{O}_S \rangle$

FOR THE SPECIAL CASE $\frac{\partial}{\partial t} H_S = 0 \Rightarrow U_S = e^{-\frac{i}{\hbar}(t-t_0)H_S} \Rightarrow [U_S, H_S] = 0$ (4)

$$\Rightarrow H_S = H_{Ht}$$

CURIOSITY: LET $|v_S\rangle$ BE AN EIGENVECTOR OF D_S

$$\Rightarrow |v_S\rangle = U_S(t, t_0) |v_H\rangle$$

$$\Rightarrow i\hbar \frac{d}{dt} |v_S\rangle = \left(i\hbar \frac{\partial}{\partial t} U_S \right) |v_H\rangle + i\hbar U_S \frac{d}{dt} |v_H\rangle$$

$$\Rightarrow \text{(BY DEFINITION)} \quad H_S U_S |v_H\rangle$$

$$\Rightarrow i\hbar \frac{d}{dt} |v_H\rangle = -U_S^\dagger H_S U_S |v_H\rangle$$

$$\boxed{i\hbar \frac{d}{dt} |v_H\rangle = -H_{Ht} |v_H\rangle}$$

→ SCHRÖDINGER EQUATION WITH A MINUS SIGN. THE NEGATIVE SIGN IS BECAUSE $|v_H\rangle$ "ROTATES" BACKWARDS

EXERCISE: COMPUTE $i\hbar \frac{\partial}{\partial t} P_H$

$$i\hbar \frac{\partial}{\partial t} P_H \equiv i\hbar U_S^\dagger \left(\frac{\partial}{\partial t} P_S \right) U_S = -U_S^\dagger [P_S, H_S] U_S = [H_{Ht}, P_H]$$

EXERCISE: SHOW THAT $\frac{d}{dt} |v_H\rangle = 0$

$$i\hbar \frac{d}{dt} |v_H\rangle = \left(i\hbar \frac{d}{dt} U_S^\dagger \right) |v_S\rangle + U_S^\dagger \left(i\hbar \frac{d}{dt} |v_S\rangle \right) = -U_S^\dagger H_S |v_S\rangle + U_S^\dagger H_S |v_S\rangle = 0$$

• INTERACTION PICTURE

$$\text{LET } H_S(t) = H_0 + V_S(t) \quad \text{WHERE } \frac{\partial}{\partial t} H_0 = 0$$

$$\text{DICTIONARY: } D_I = U_0^\dagger(t, t_0) D_S U_0(t, t_0) = e^{\frac{i}{\hbar}(t-t_0)H_0} D_S e^{-\frac{i}{\hbar}(t-t_0)H_0}$$

NOTICE THAT $H_{0,S} \equiv H_0 = H_{0,I}$, SINCE $[H_0, U_0] = 0$

* THE DYNAMICS OF D_I IS DICTATED BY H_0 (OR $H_{0,S}$) (WHICH MAY BE SIMPLE)

$$i\hbar \frac{d}{dt} D_I = (-U_0^\dagger H_0) D_S U_0 + U_0^\dagger D_S (H_0 U_0) + i\hbar U_0^\dagger \left(\frac{\partial}{\partial t} D_S \right) U_0 \equiv \frac{\partial}{\partial t} D_I$$

$$\Rightarrow \boxed{i\hbar \frac{d}{dt} O_I = [O_I, H_0] + i\hbar \frac{\partial}{\partial t} O_I}$$

DICTIONARY: $|\Psi_I(t)\rangle = U_0^\dagger(t, t_0) |\Psi_S(t)\rangle$

THEREFORE, $\langle O_I \rangle = \langle \Psi_I | O_I | \Psi_I \rangle = \langle \Psi_S | U_0 U_0^\dagger O_I U_0 U_0^\dagger | \Psi_S \rangle = \langle \Psi_S | O_S | \Psi_S \rangle = \langle O_S \rangle$

TIME DEPENDENCE OF $|\Psi_I\rangle$:

$$\begin{aligned} i\hbar \frac{d}{dt} |\Psi_I\rangle &= \left(i\hbar \frac{d}{dt} U_0^\dagger \right) |\Psi_S\rangle + U_0^\dagger \left(i\hbar \frac{d}{dt} |\Psi_S\rangle \right) = -U_0^\dagger H_0 |\Psi_S\rangle + U_0^\dagger H_S |\Psi_S\rangle \\ &= U_0^\dagger V_S |\Psi_S\rangle = U_0^\dagger V_S U_0 U_0^\dagger |\Psi_S\rangle \end{aligned}$$

$$\Rightarrow \boxed{i\hbar \frac{d}{dt} |\Psi_I\rangle = V_I(t) |\Psi_I\rangle} \quad \text{DYNAMICS IS DICTATED BY THE INTERACTION } V_I(t)$$

- * FOR $V(t) = 0 \Rightarrow$ RECOVERS THE HEISENBERG PICTURE
- * FOR $H_0 = 0 \Rightarrow$ " " SCHRODINGER "

EXERCISE: SHOW THAT $U_{II}(t, t_0) = 1$

FOR $V_S = 0 \Rightarrow U_I = U_{II}$, MOREOVER $U_0 = U_I = e^{-\frac{i}{\hbar}(t-t_0)H_0}$

TIME-DEPENDENT EQUATION FOR U_I :

$$i\hbar \frac{d}{dt} U_I = (-H_0 U_0^\dagger) U_S U_0 + U_0^\dagger U_S (H_0 U_0) + U_0^\dagger (H_S U_S) U_0$$

TIME-EVOLUTION OPERATOR: WE WANT $|\Psi_I(t)\rangle = U_I(t, t_0) |\Psi_I(t_0)\rangle$

WE KNOW THAT $|\Psi_I(t)\rangle = U_0^\dagger(t, t_0) |\Psi_S(t)\rangle = U_0^\dagger(t, t_0) U_S(t, t_0) |\Psi_S(t_0)\rangle = U_0^\dagger(t, t_0) U_S(t, t_0) U_0(t_0, t_0) |\Psi_I(t_0)\rangle$

$$\Rightarrow \boxed{U_I(t, t_0) = U_0^\dagger(t, t_0) U_S(t, t_0) = U_0^\dagger(t, t_0) U_S(t, t_0) U_0(t_0, t_0)}$$

NOTICE IT IS SLIGHTLY DIFFERENT FROM $O_I = U_0^\dagger O_S U_0(t, t_0)$

$$\Rightarrow i\hbar \frac{d}{dt} U_I = -H_0 U_0^\dagger(t, t_0) U_S(t, t_0) + U_0^\dagger(t, t_0) H_S U_S(t, t_0)$$

$$\Rightarrow \boxed{i\hbar \frac{d}{dt} U_I(t, t_0) = V_I(t) U_I(t, t_0)}$$

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 IN SOME BOOKS, THE INTERACTION PICTURE MAY APPEAR DEFINED IN A SLIGHTLY DIFFERENT MANNER:

THE DICTIONARY IS

$$\begin{cases} O_I = T_0^+(t) O_S T_0(t) \\ |\Psi_I(t)\rangle = T_0^+(t) |\Psi_S(t)\rangle \end{cases}$$

with $T_0(t) = e^{-i \frac{H_0}{\hbar} t}$

WITH THIS MODIFICATION, WE THEN HAVE THAT

• $i\hbar \frac{d}{dt} O_I = [O_I, H_0] + i\hbar \frac{\partial}{\partial t} O_I$ (STILL THE SAME)

• $i\hbar \frac{d}{dt} |\Psi_I\rangle = V_I |\Psi_I\rangle$ (STILL THE SAME)

• $|\Psi_I(t)\rangle = U_I(t, t_0) |\Psi_I(t_0)\rangle = T_0^+(t) |\Psi_S(t)\rangle = T_0^+(t) U_S(t, t_0) |\Psi_S(t_0)\rangle$
 $= T_0^+(t) U_S(t, t_0) T_0(t_0) |\Psi_I(t_0)\rangle$

$\Rightarrow U_I(t, t_0) = T_0^+(t) U_S(t, t_0) T_0(t_0)$ (SLIGHTLY DIFFERENT)

THIS SEEMS A MORE APPEALING WAY OF DEFINING THE INTERACTION PICTURE BECAUSE THE TIME EVOLUTION OPERATOR TRANSFORMS MORE LIKELY THE USUAL OPERATORS. BUT EITHER WAY OF DEFINING THE PICTURE YIELDS TO THE SAME RESULTS, AS SHOULD BE.

• FINALLY, $i\hbar \frac{d}{dt} U_I = -H_0 T_0^+(t) U_S T_0(t) + \cancel{T_0^+(t) U_S T_0(t) H_0} T_0^+(t) H_S U_S T_0(t)$

$\Rightarrow i\hbar \frac{d}{dt} U_I = V_I(t) U_I(t, t_0)$ (STILL THE SAME)

FOR THE PURPOSES OF BUILDING A PERTURBATION THEORY FRAMEWORK, BOTH DEFINITIONS OF THE INTERACTING PICTURE GIVE THE SAME RESULTS. THE ONE IN THIS PAGE MAY BE A LITTLE MORE CONVENIENT BECAUSE IT HELPS WITH THE ALGEBRA.